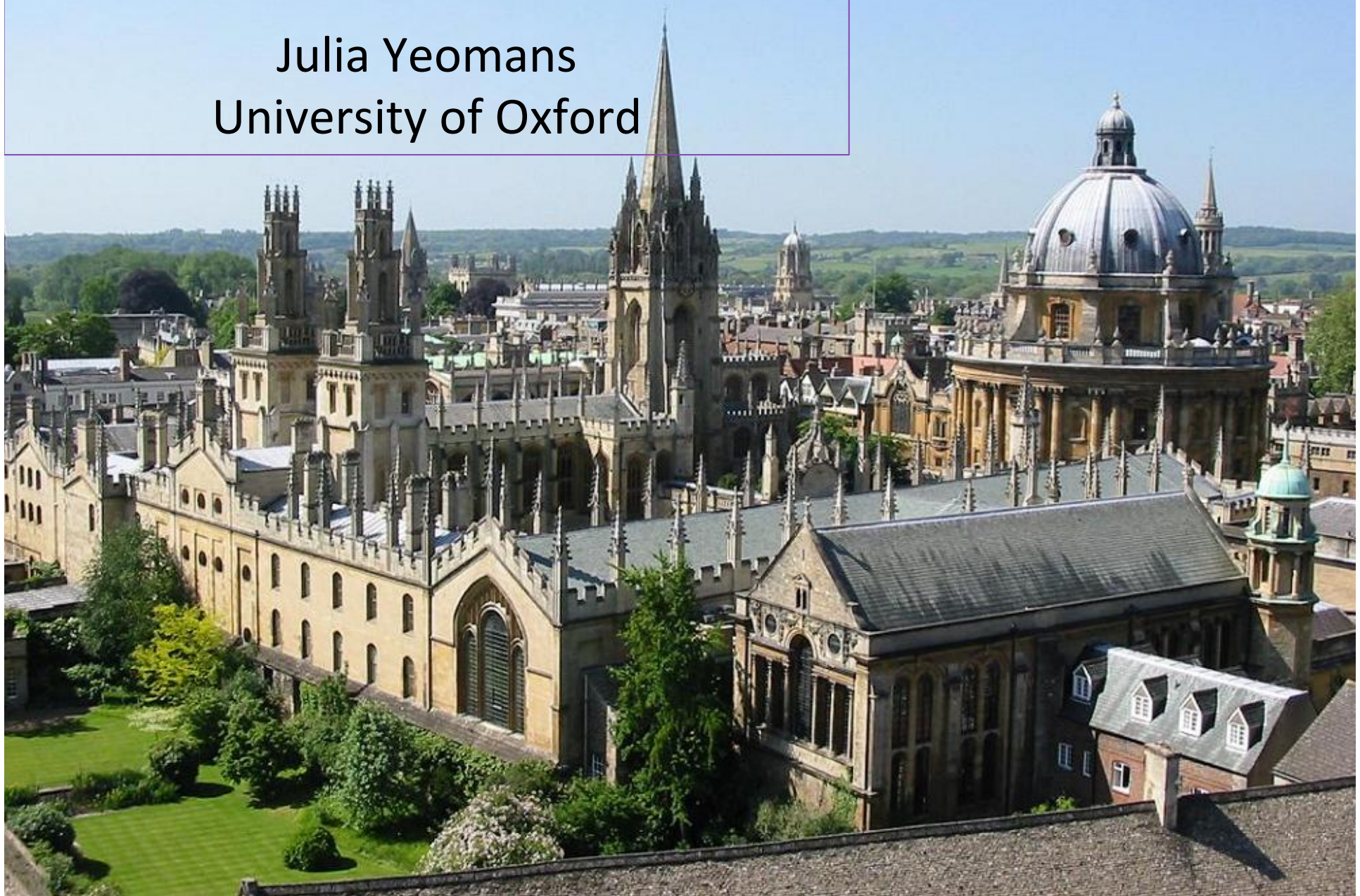


The Hydrodynamics of Active Matter

Julia Yeomans
University of Oxford



Lecture 1: The mathematics and physics of bacterial swimming

1. Low Re and the Stokes equations

2. The Scallop theorem

one active particle

3. Dipolar flow fields

4. Multipole expansion for the Stokes equations

Lecture 2: Applications

1. Swimming in Poiseuille flow and ...taxis

2. Stirring by microswimmers

Lecture 3: Continuum models of dense active matter

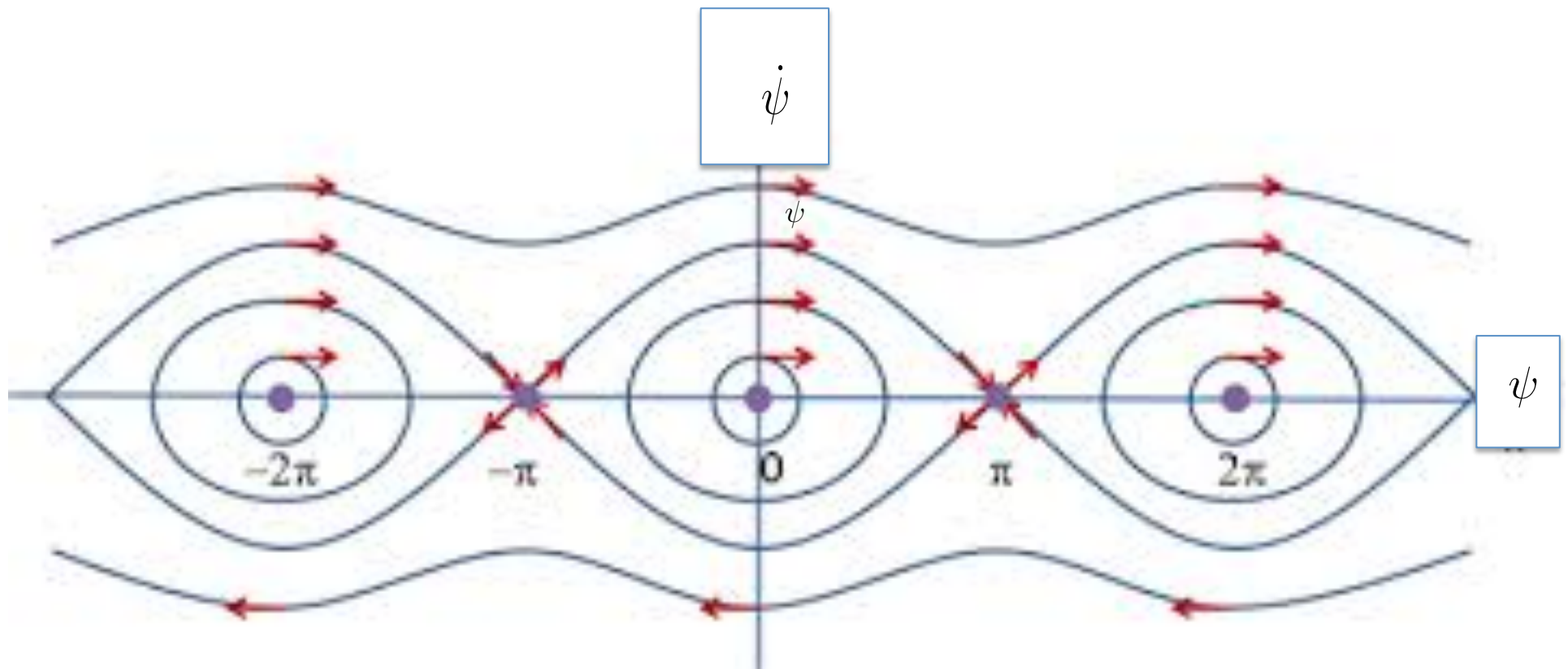
lots of active particles

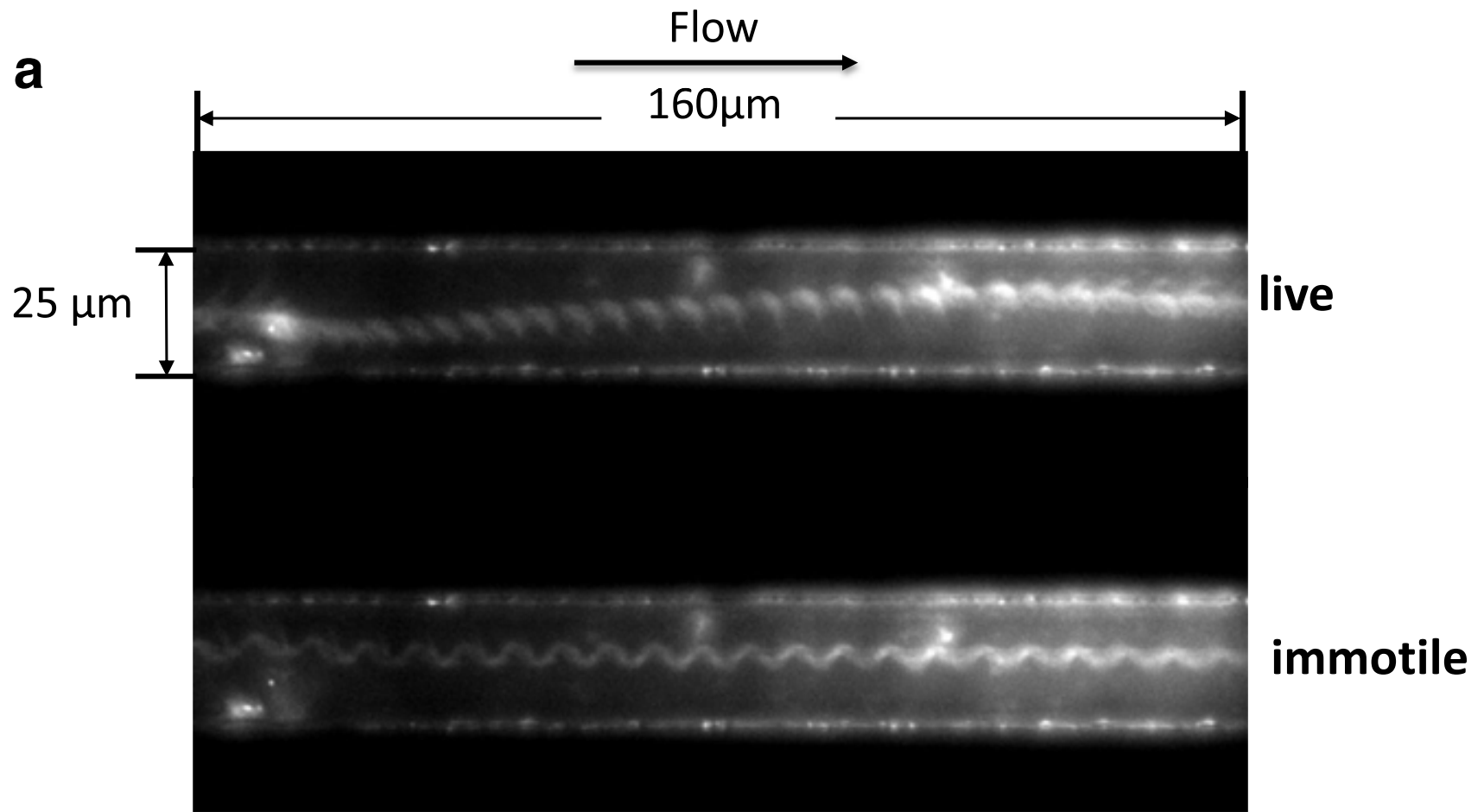
Lecture 4: Active turbulence and lyotropic active nematics

Phase portrait of a pendulum

$$\ddot{\psi} + \sin \psi = 0.$$

$$\dot{x} = -\sin \psi, \quad \dot{\psi} = x$$





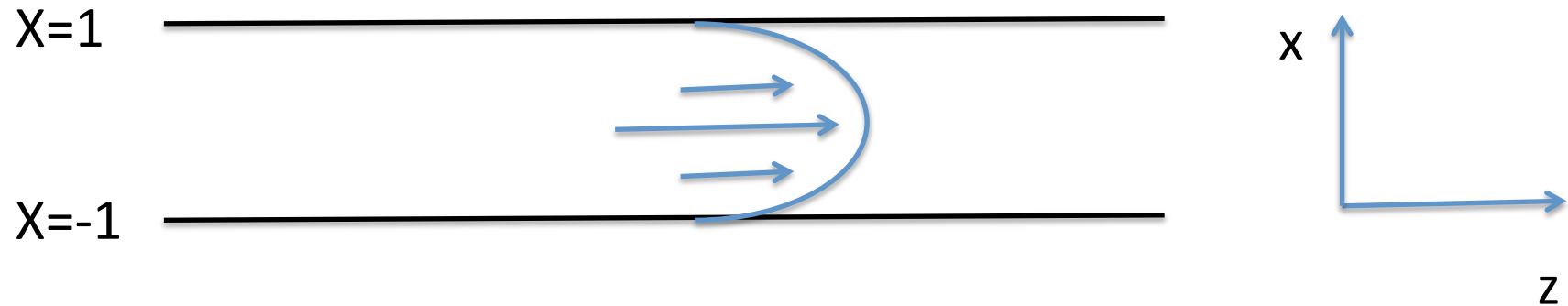
b

Flow velocity 1.6mm/s @ 300Hz

Typanosome

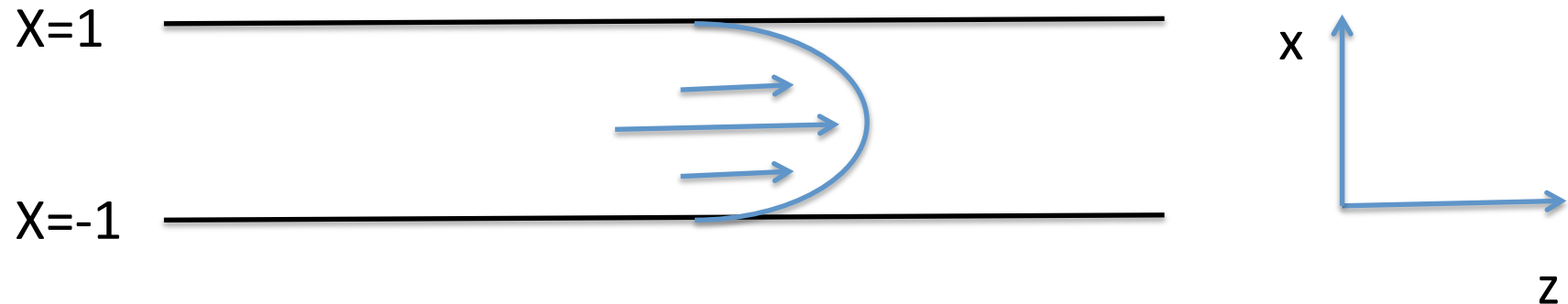
Uppaluri Biophys J (2012)

Poiseuille flow and notation



$$\mathbf{v}_f = v_f(1 - x^2)\hat{\mathbf{z}}$$

Poiseuille flow and notation



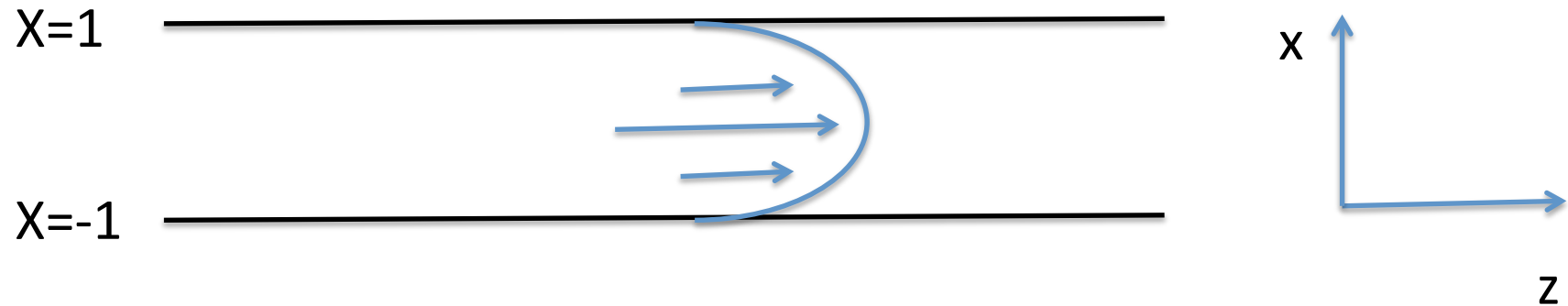
$$\mathbf{v}_f = v_f(1 - x^2)\hat{\mathbf{z}}$$

vorticity

$$\begin{aligned}\boldsymbol{\Omega}_f &= \nabla \wedge \mathbf{v}_f \\ &= (0, 2xv_f, 0)\end{aligned}$$

Zottl and Stark, Phys Rev Lett 108 (2012)

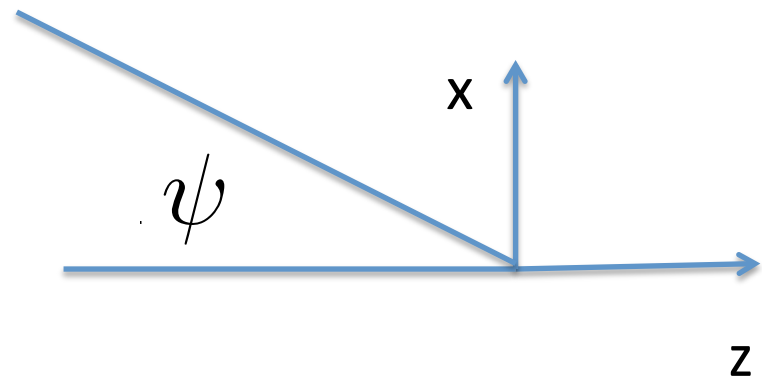
Poiseuille flow and notation



$$\mathbf{v}_f = v_f(1 - x^2)\hat{\mathbf{z}}$$

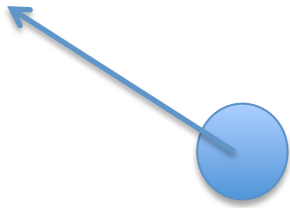
vorticity

$$\begin{aligned}\boldsymbol{\Omega}_f &= \nabla \wedge \mathbf{v}_f \\ &= (0, 2xv_f, 0)\end{aligned}$$



Zottl and Stark, Phys Rev Lett 108 (2012)

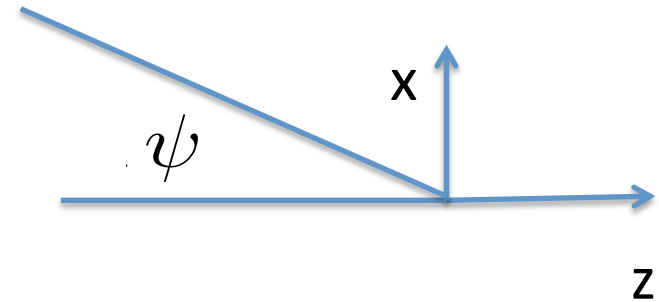
Swimmer model



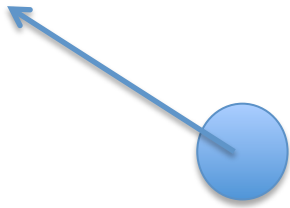
$$\hat{\mathbf{e}} = -\sin \psi \hat{\mathbf{x}} - \cos \psi \hat{\mathbf{z}},$$

speed

v_0

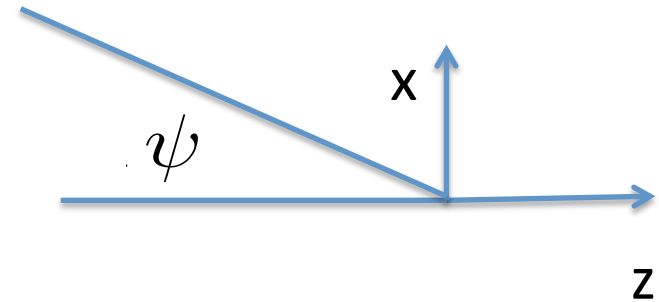


Swimmer model



$$\hat{\mathbf{e}} = -\sin \psi \hat{\mathbf{x}} - \cos \psi \hat{\mathbf{z}},$$

speed v_0



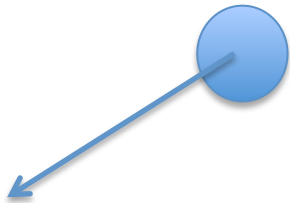
$$\frac{d}{dt} \mathbf{r} = v_0 \hat{\mathbf{e}} + \mathbf{v}_f,$$

$$\frac{d}{dt} \hat{\mathbf{e}} = \frac{1}{2} \boldsymbol{\Omega}_f \wedge \hat{\mathbf{e}}.$$

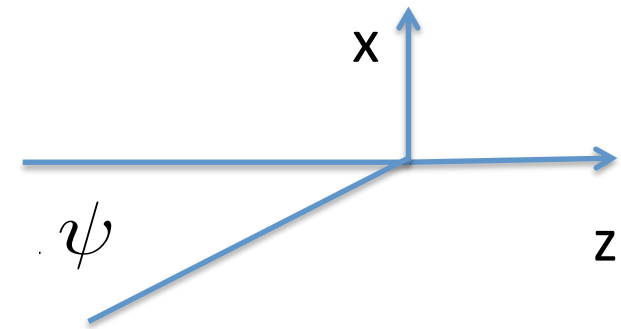
Swimmer model

direction

$$\hat{\mathbf{e}} = -\sin \psi \hat{\mathbf{x}} - \cos \psi \hat{\mathbf{z}},$$



speed v_0



$$\frac{d}{dt} \mathbf{r} = v_0 \hat{\mathbf{e}} + \mathbf{v}_f,$$

$$\frac{d}{dt} \hat{\mathbf{e}} = \frac{1}{2} \boldsymbol{\Omega}_f \wedge \hat{\mathbf{e}}.$$

1

NB scale time with v_0

2

$$\hat{\mathbf{e}} = -\sin \psi \hat{\mathbf{x}} - \cos \psi \hat{\mathbf{z}},$$

$$\mathbf{v}_f = v_f(1 - x^2)\hat{\mathbf{z}}$$



$$\frac{d}{dt}\mathbf{r} = \hat{\mathbf{e}} + \frac{\mathbf{v}_f}{v_0}$$

x-component

$$\frac{d}{dt}x = -\sin \psi$$

z-component

$$\frac{d}{dt}z = -\cos \psi + \frac{v_f}{v_0}(1 - x^2)$$

$$\boldsymbol{\Omega}_f = \nabla \wedge \mathbf{v}_f = (0, 2xv_f, 0)$$

$$\hat{\mathbf{e}} = -\sin \psi \hat{\mathbf{x}} - \cos \psi \hat{\mathbf{z}},$$



$$\frac{d}{dt} \hat{\mathbf{e}} = \frac{1}{2v_0} \boldsymbol{\Omega}_f \wedge \hat{\mathbf{e}}.$$

x-component

$$-\cos \psi \dot{\psi} = -\frac{xv_f \cos \psi}{v_0}$$

z-component

$$+\sin \psi \dot{\psi} = \frac{xv_f \sin \psi}{v_0}$$

$$\frac{d\psi}{dt} = \frac{v_f}{v_0} x$$

$$\frac{d}{dt} x = -\sin \psi$$

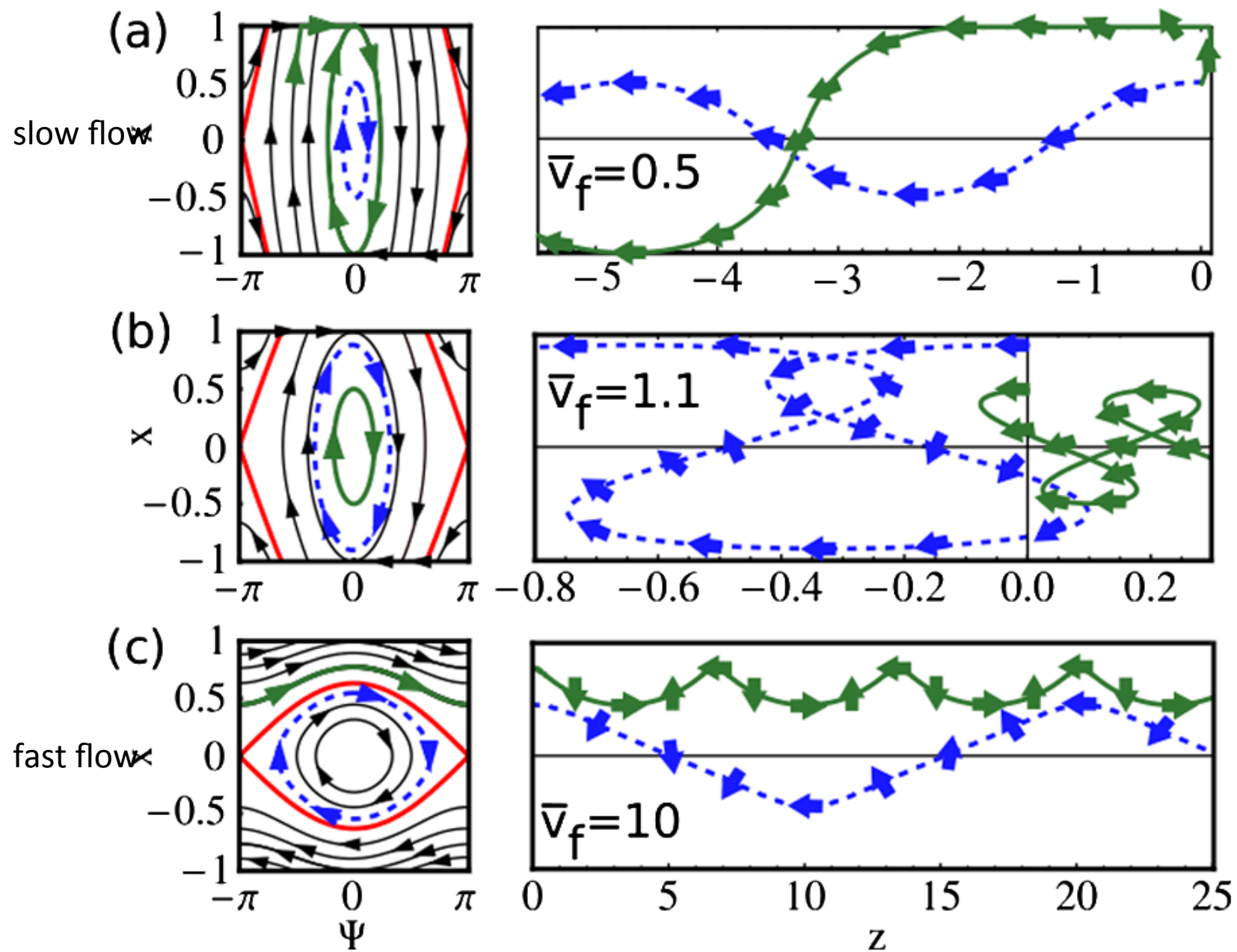
$$\frac{d}{dt} z = -\cos \psi + \frac{v_f}{v_0} (1 - x^2)$$

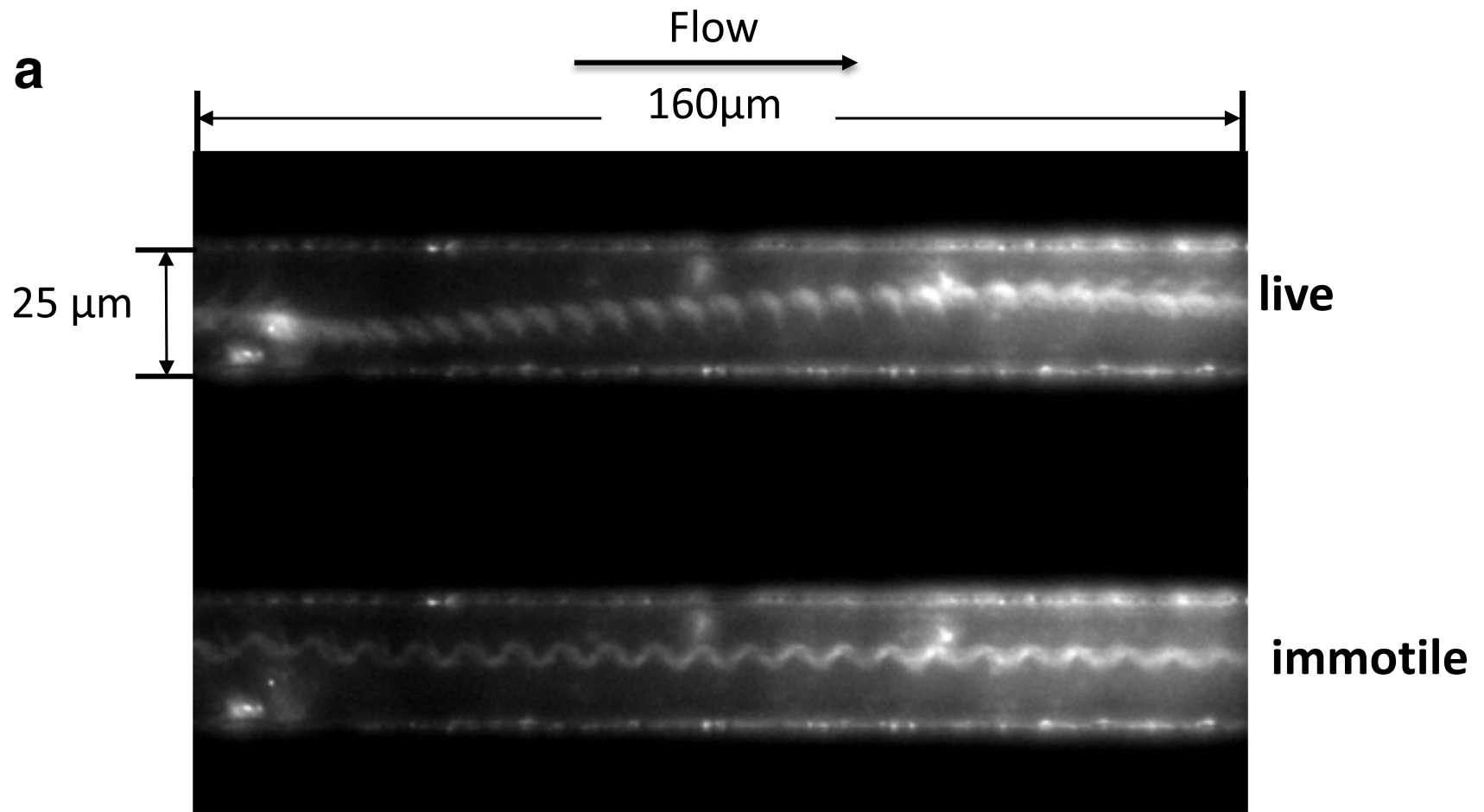
$$\frac{d\psi}{dt} = \frac{v_f}{v_0} x$$

$$\frac{d}{dt} x = -\sin \psi$$

$$\ddot{\psi} + \frac{v_f}{v_0} \sin \psi = 0.$$

$$\frac{d}{dt} z = -\cos \psi + \frac{v_f}{v_0} (1 - x^2)$$





b

Flow velocity 1.6mm/s @ 300Hz

Typannosome

Uppaluri Biophys J (2012)

what is missing?

3D

interactions with walls

swimmer size and shape

fluctuations

...taxis

alignment with a given direction

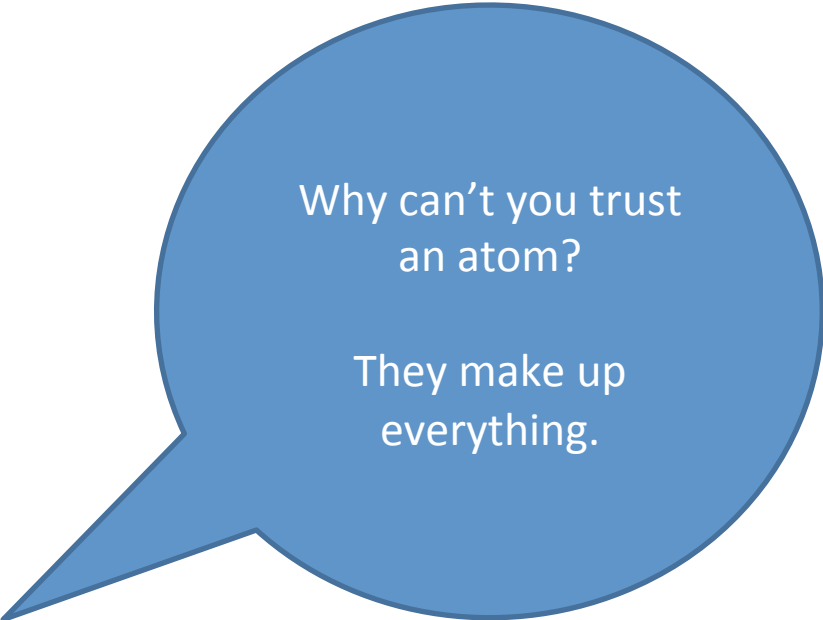
gravitaxis – like to swim upwards

chemotaxis – follow a chemical gradient

magnetotaxis – follow a magnetic field

rheotaxis – shear + gravity

phototaxis – follow light



Why can't you trust
an atom?

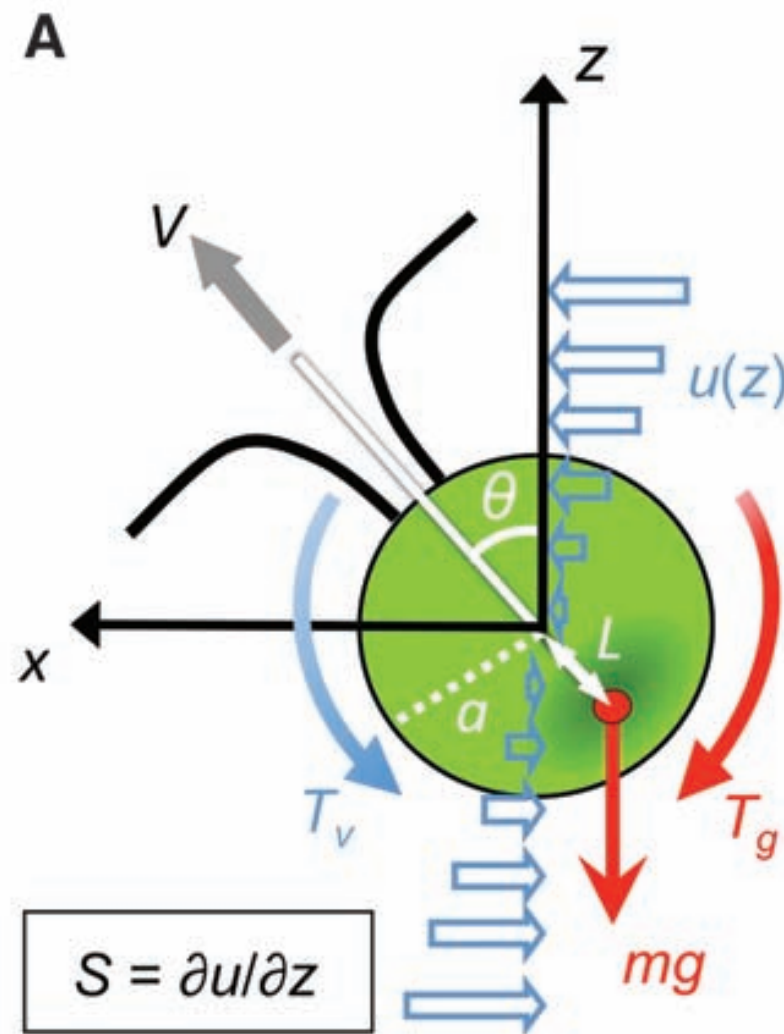
They make up
everything.

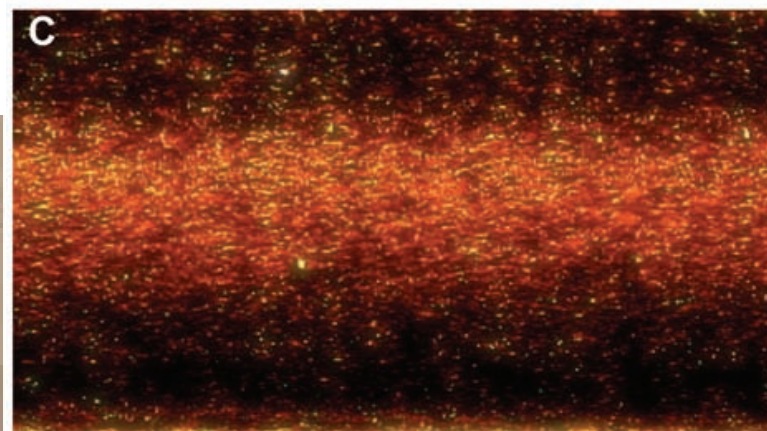
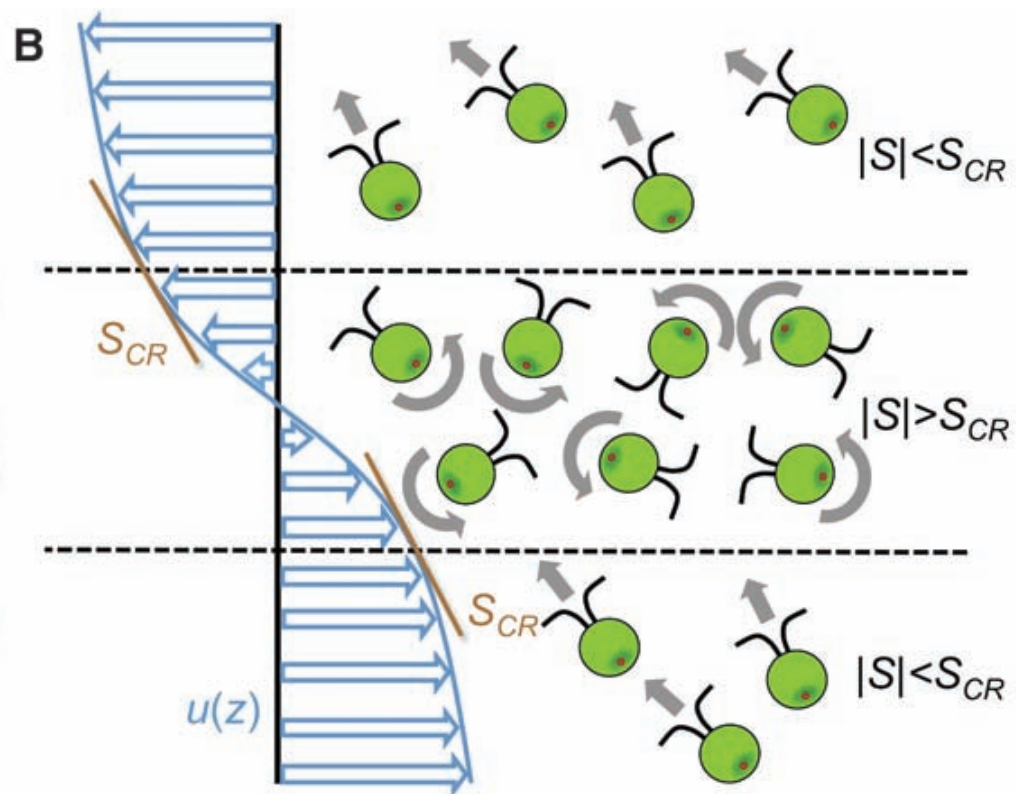
...taxis

$$\frac{d}{dt}\hat{\mathbf{e}} = \frac{1}{2}\{\boldsymbol{\Omega}_f \wedge \hat{\mathbf{e}} + \frac{1}{\beta}(\hat{\mathbf{z}} - (\hat{\mathbf{z}} \cdot \hat{\mathbf{e}})\hat{\mathbf{e}})\}$$

$$\sin \theta = \beta \Omega$$

Durham, Kessler, Stocker
Science 323 (2009)





Lecture 1: The mathematics and physics of bacterial swimming

1. Low Re and the Stokes equations

2. The Scallop theorem

one active particle

3. Dipolar flow fields

4. Multipole expansion for the Stokes equations

Lecture 2: Applications

1. Swimming in Poiseuille flow and ...taxis

2. Stirring by microswimmers

Lecture 3: Continuum models of dense active matter

lots of active particles

Lecture 4: Active turbulence and lyotropic active nematics

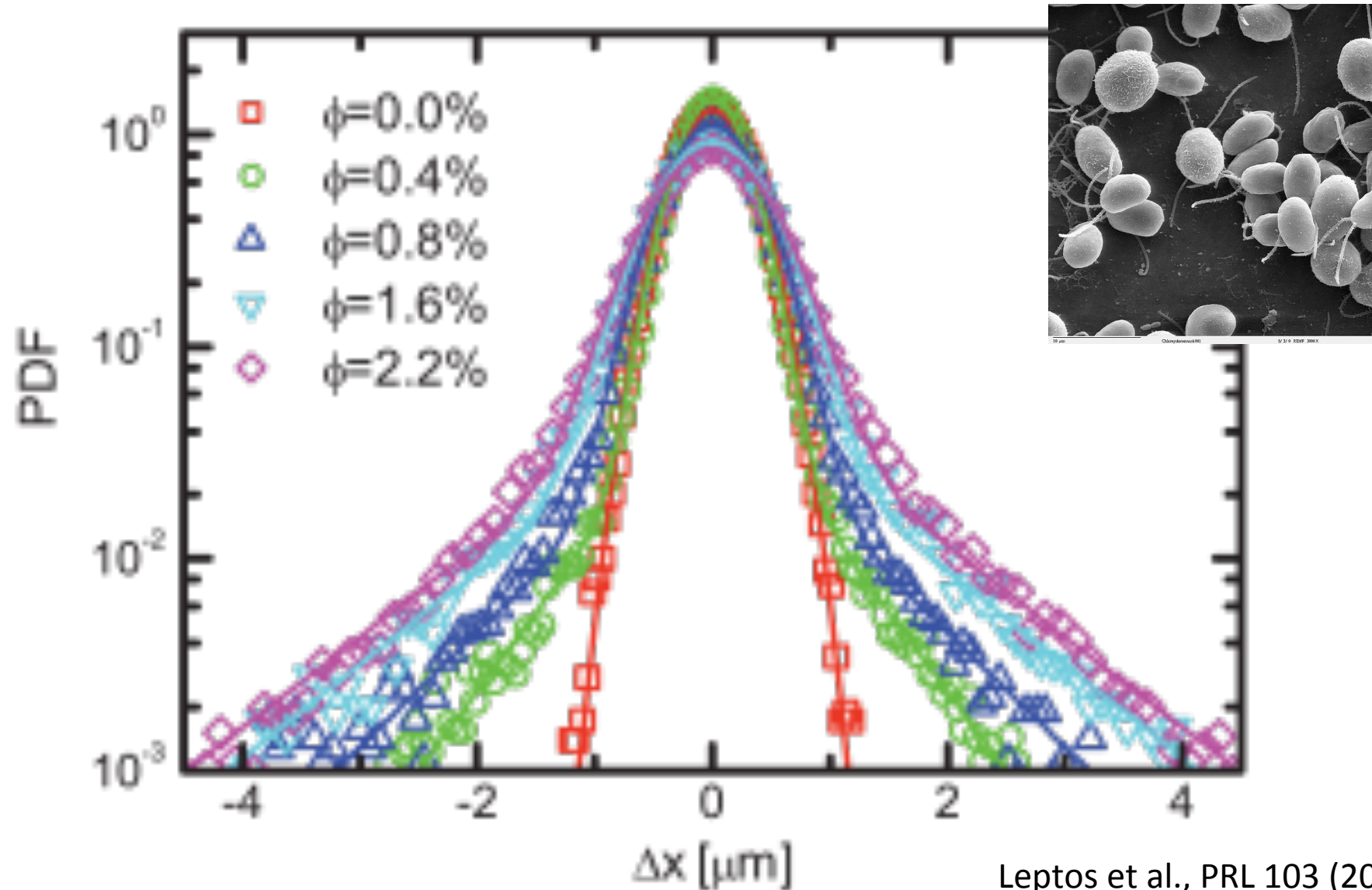
Stirring by microswimmers

Do microswimmers stir the fluid they swim in?

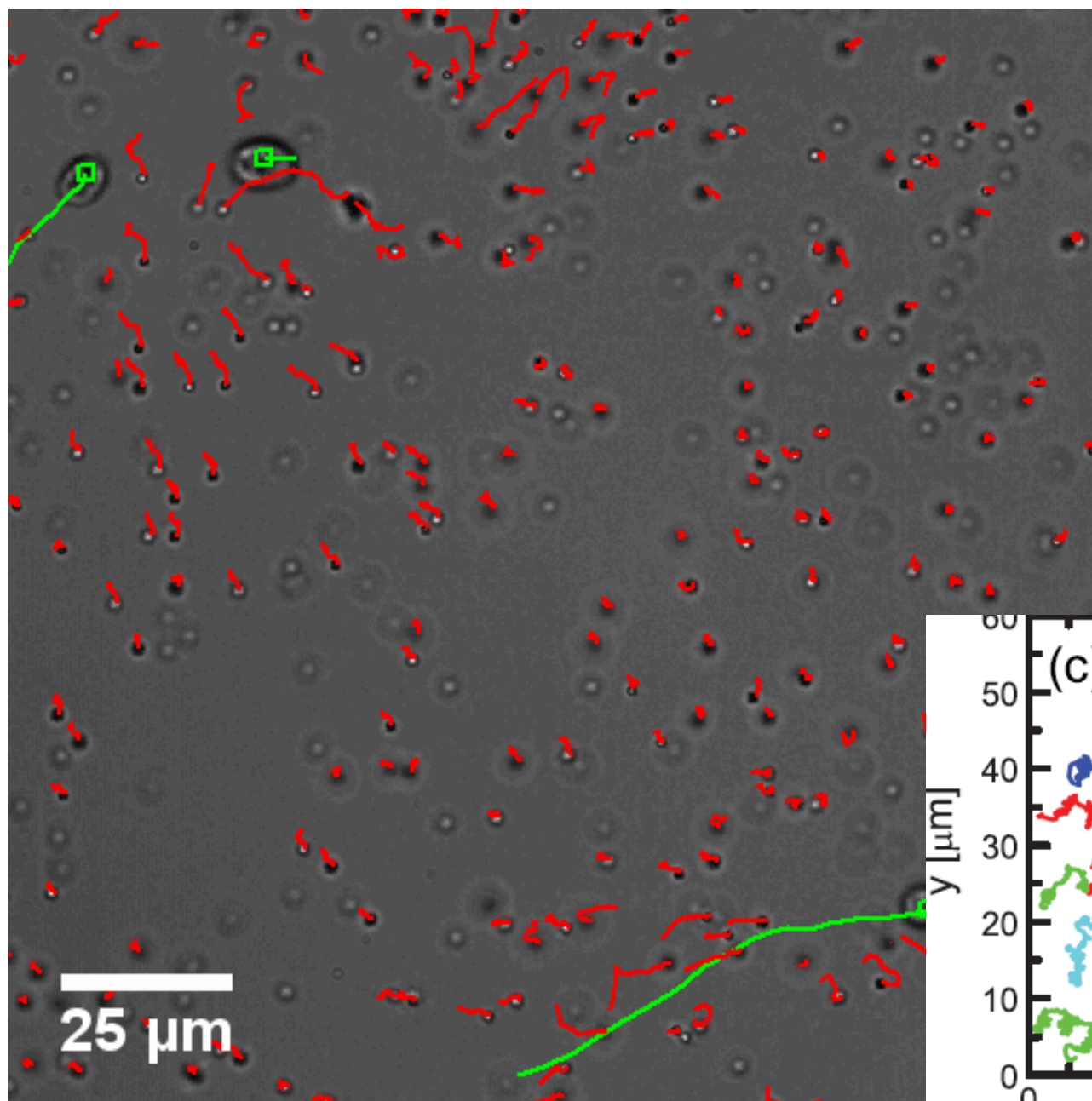
Why do microswimmers stir the fluid they swim in?

How do microswimmers stir the fluid they swim in?

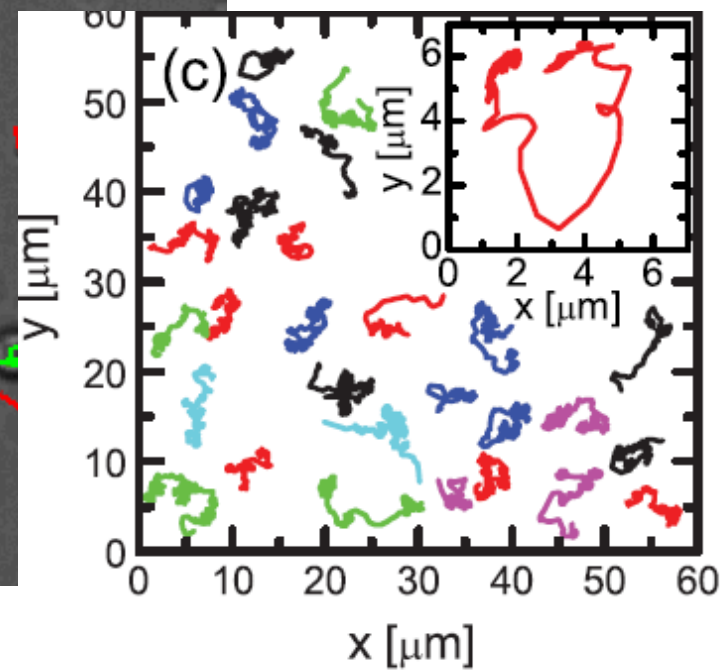
Swimmers enhance diffusion



Leptos et al., PRL 103 (2009)



Guasto website

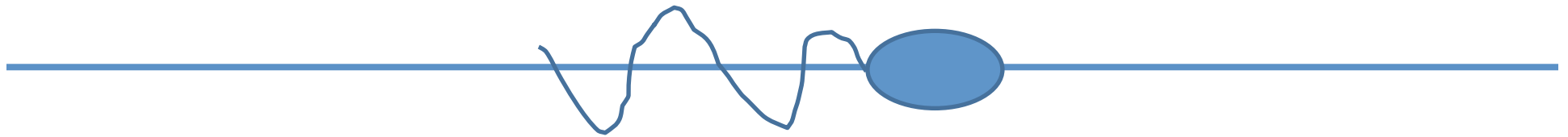


Stirring by microswimmers

Do microswimmers stir the fluid they swim in?

Why do microswimmers stir the fluid they swim in?

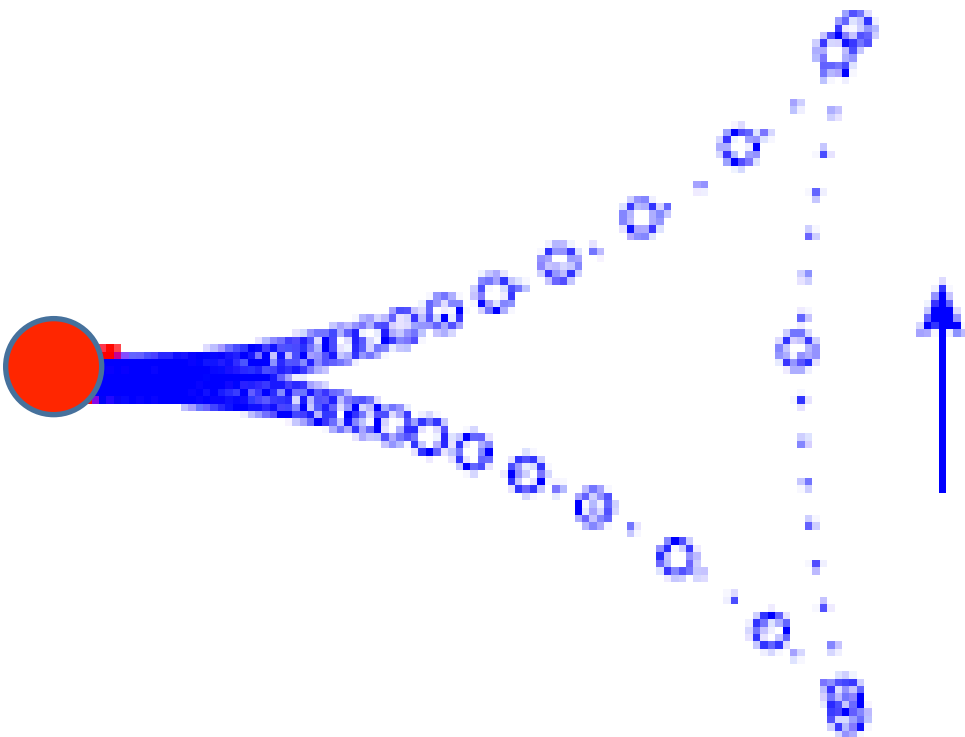
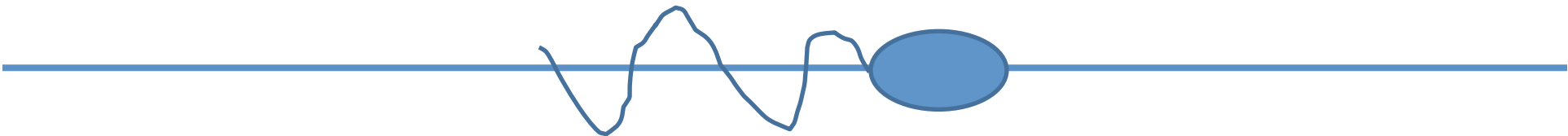
How do microswimmers stir the fluid they swim in?



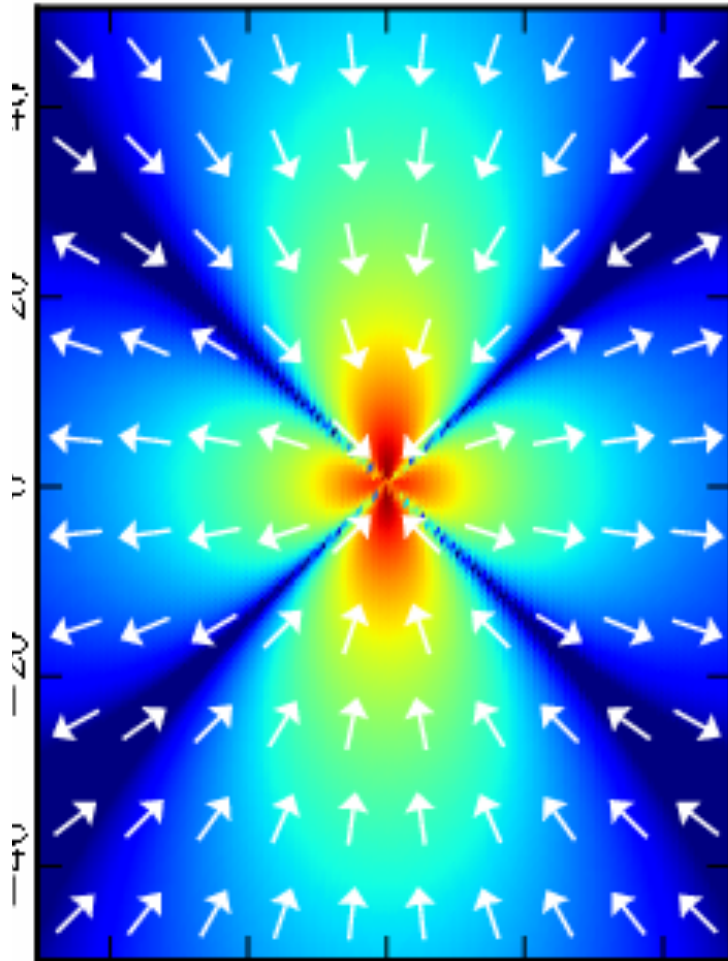
Where does bad light
end up?

In a prism.

Fluid transport by individual microswimmers,
D.O. Pushkin, H. Shum and J. M. Yeomans,
Journal of Fluid Mechanics **726** 5 (2013).

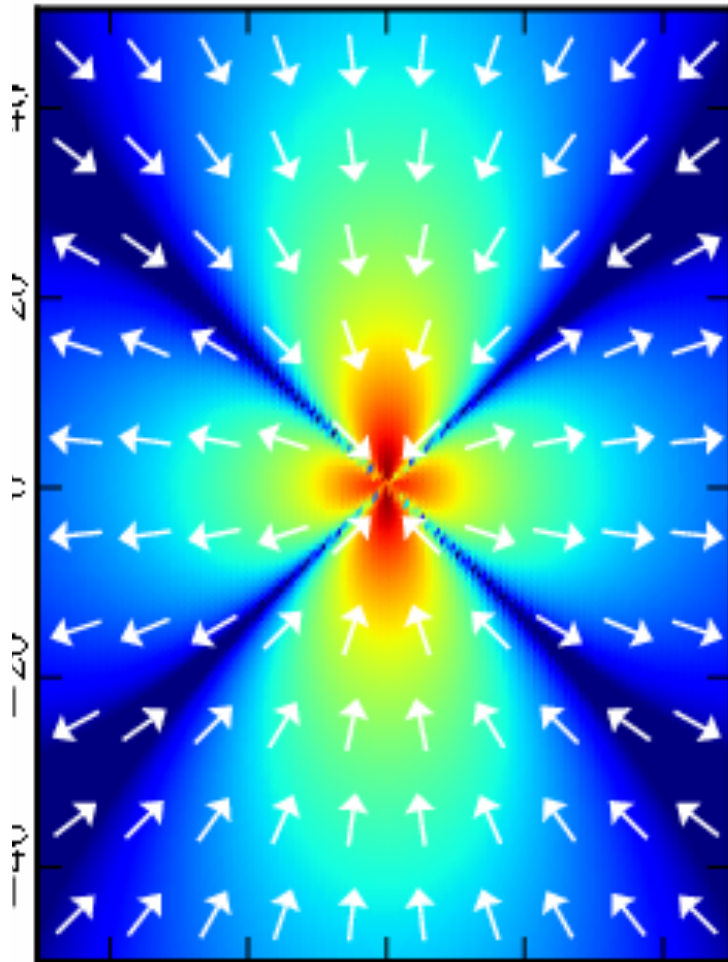


Multipole flow fields

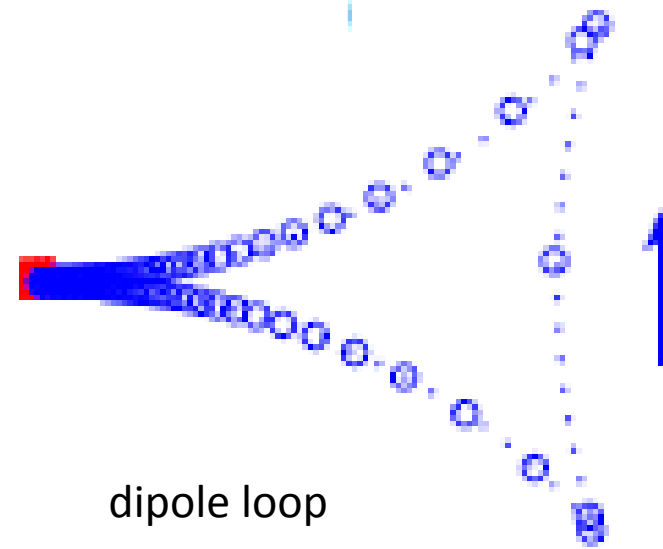


Dipole flow field

Multipole flow fields

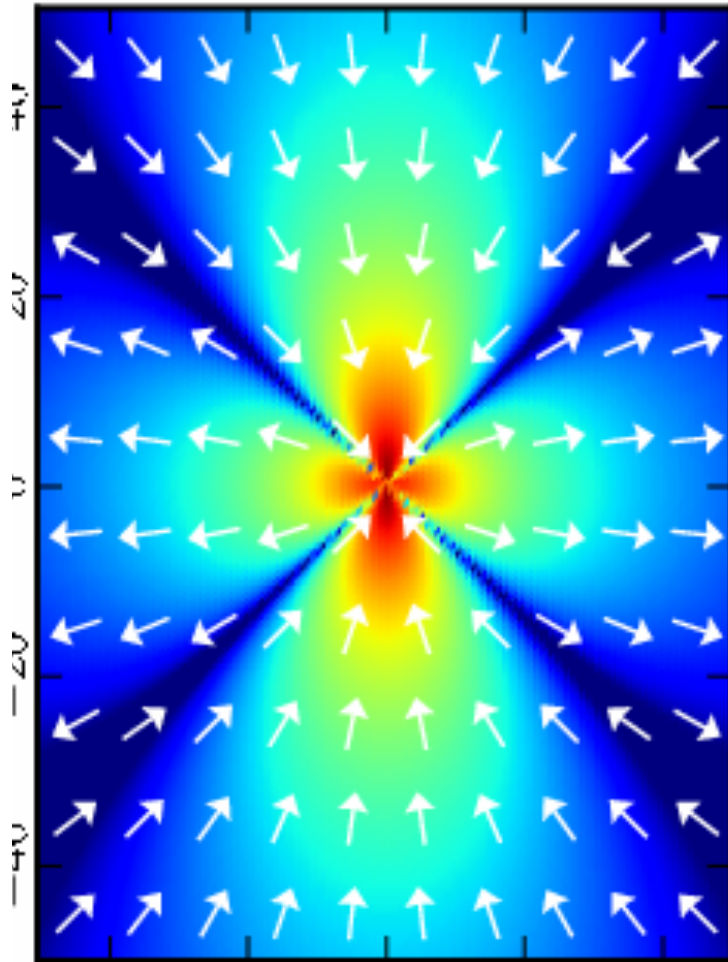


Dipole flow field

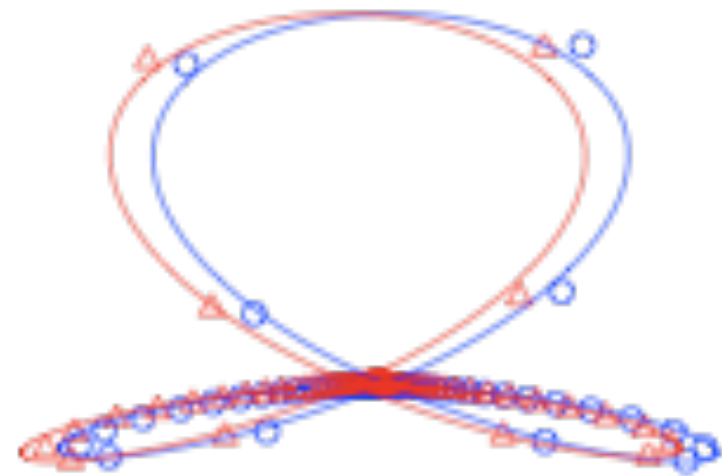
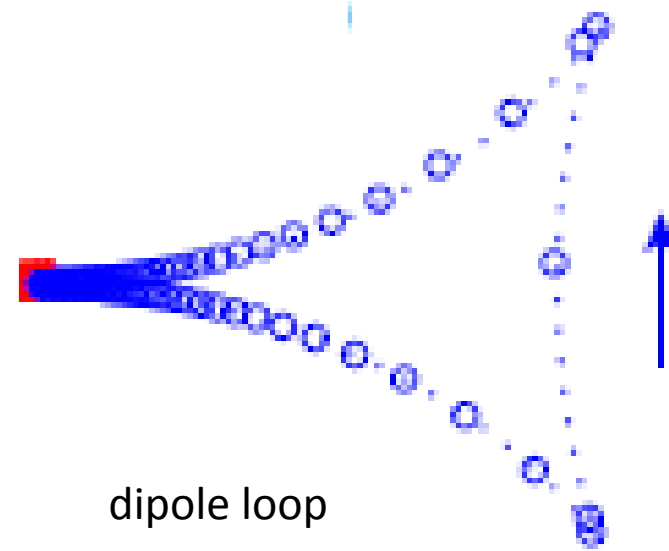


dipole loop

Multipole flow fields



Dipole flow field



quadrupole loop

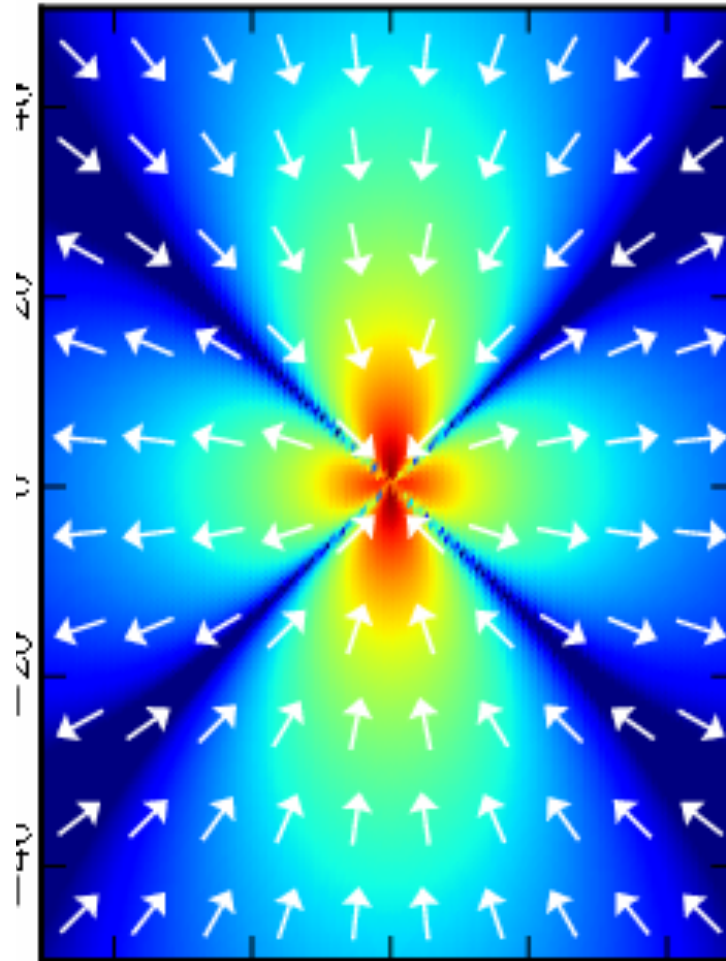
?? enhanced diffusion and loops ??



Entrainment

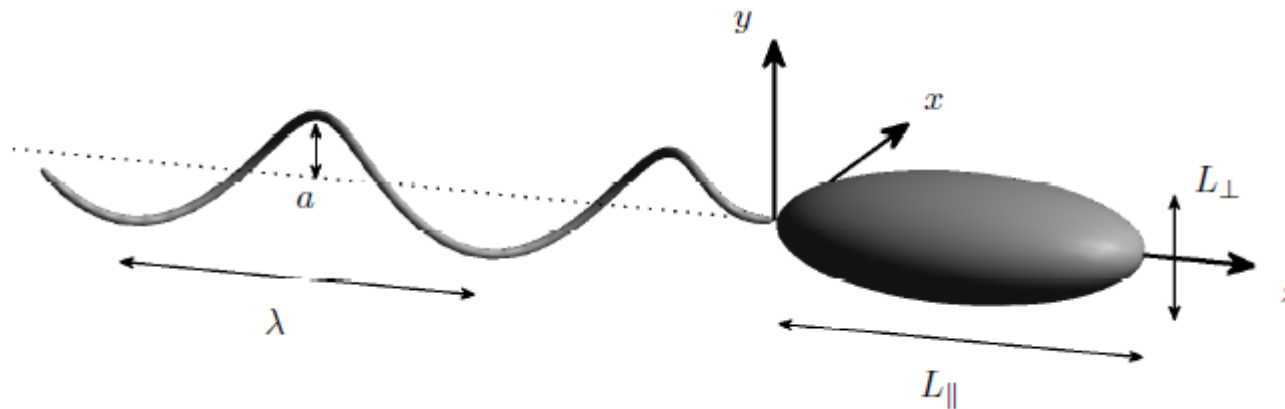
Swimmer re-orientations

Entrainment



Dipole flow field

Rhodobacter sphaeroides



Boundary element simulations

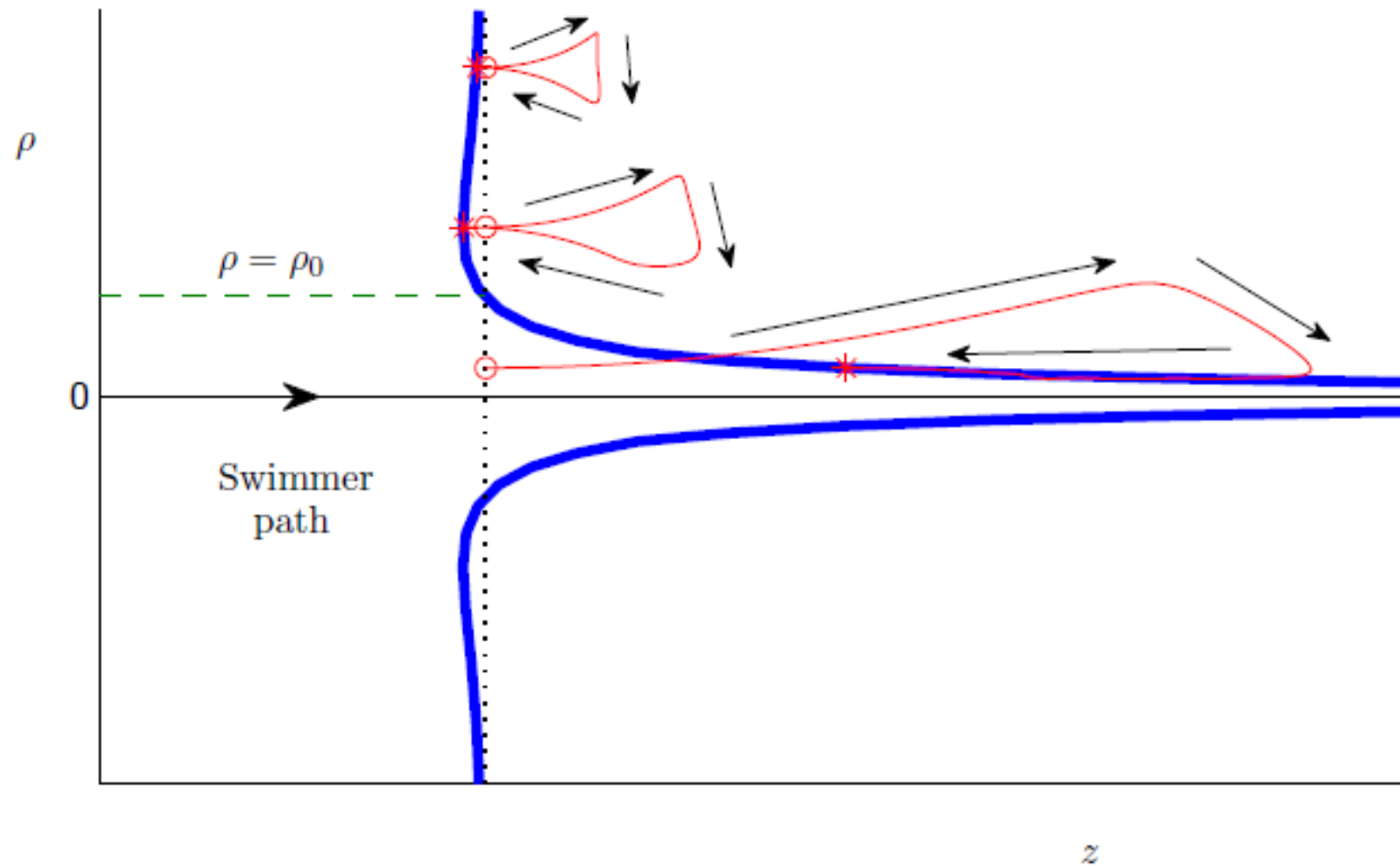
Solve Stokes equations, no slip on swimmer surface, swimmer force and torque free

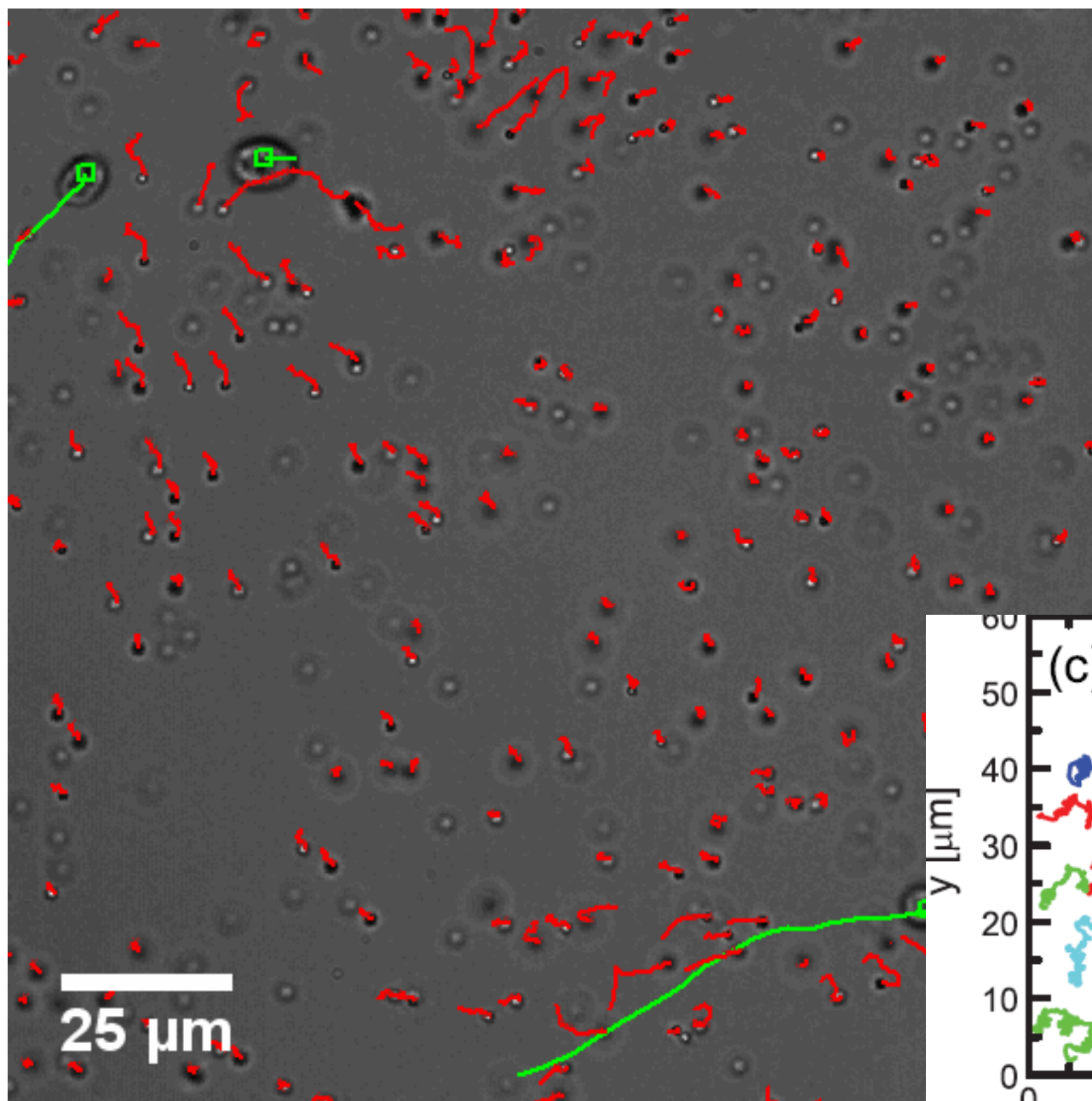
Swimmer radius 1; swimmer velocity 1; ~ 10 rotations of tail to advance one body length

Net tracer displacement along z – deviations from the z -direction very small

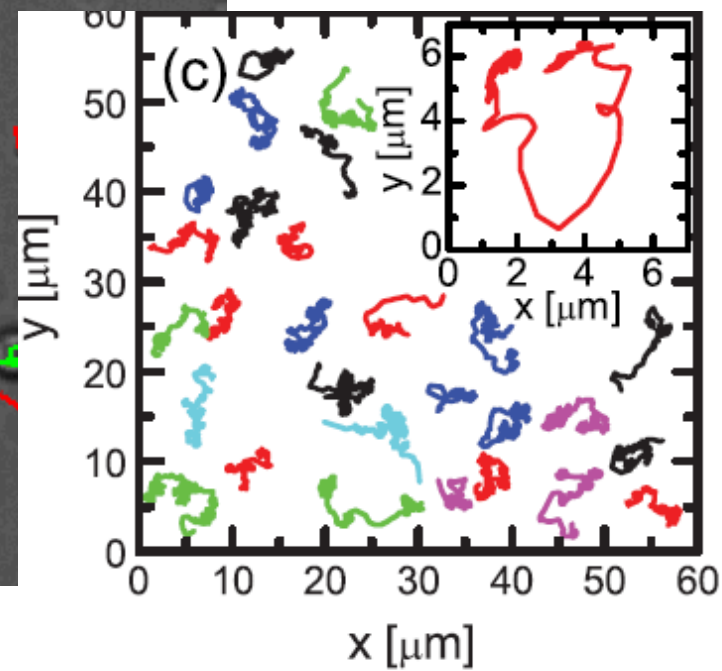
Swimmer moves from $z = -1000$ to $z = +1000$, and extrapolate to infinite swimmer path

Darwin drift

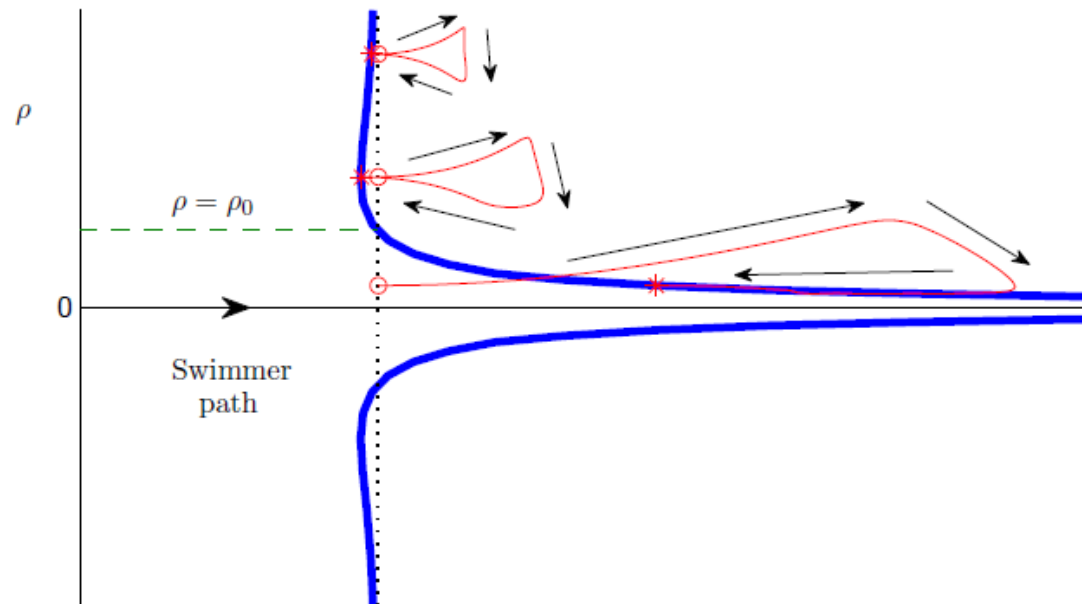




Guasto website



Darwin drift



Darwin
Benjamin
Eames
Belcher
Hunt
Gobby
Dalziel
Leshansky
Pismen

Total fluid volume moved by swimmer

Darwin drift:

$$v_D = \frac{4\pi Q_\perp}{V} - v_*,$$

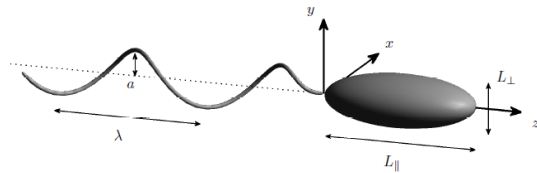
$$v_* = v_s + v_{wake}$$

$$Q_\perp = -\frac{1}{2} \int_S f_z \rho^2 dS$$

Comparison of analytic and numerical results for the Darwin drift

TABLE 1. Base parameters: $L_{\parallel}/L_{\perp} = 2$, $\lambda = 2$, $L = 10$, $a = \lambda/2\pi$.

Shape	Q_{\perp}/V	v_D (from equation)	v_D (from simulations)
Base	-0.15	-6.10	-6.11
$L_{\parallel}/L_{\perp} = 0.5$	-0.68	-12.74	-12.78
$L_{\parallel}/L_{\perp} = 3.5$	-0.08	-5.24	-5.33
$L = 5$	-0.17	-6.36	-6.30
$L = 15$	-0.14	-5.98	-6.03
$\lambda = 0.5$	-0.20	-6.76	-6.78
$\lambda = 3.5$	-0.04	-4.71	-4.68
$\lambda = 8, L = 20$	0.58	3.04	3.07



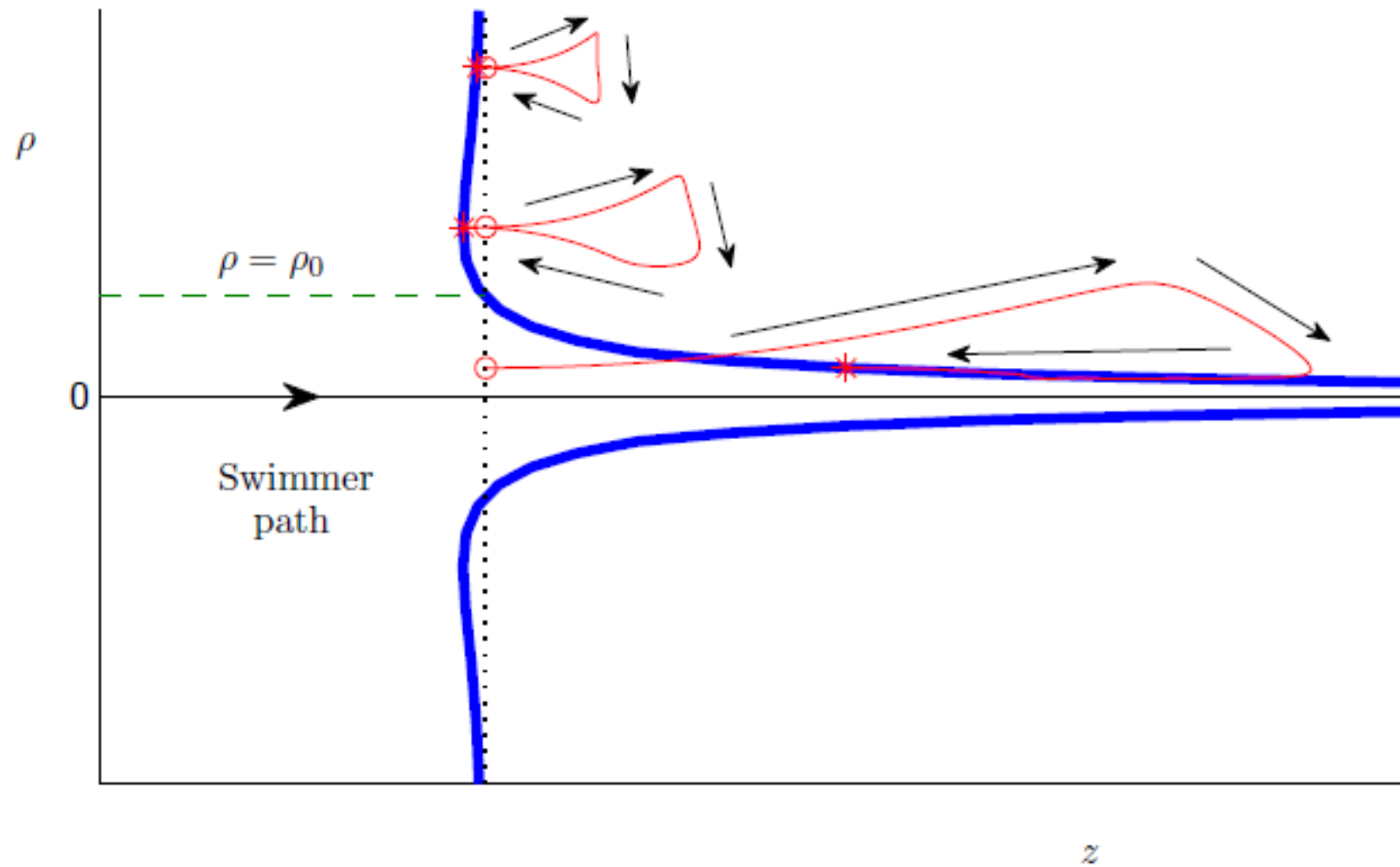
$$Q_{\perp} = -\frac{1}{2} \int_S f_z \rho^2 dS$$

Darwin drift:

$$v_D = \frac{4\pi Q_{\perp}}{V} - v_*,$$

$$v_* = v_s + v_{wake}$$

Darwin drift

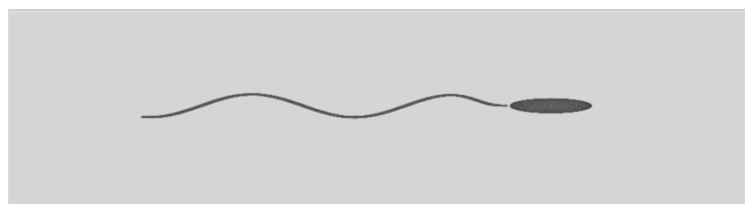


Comparison of analytic and numerical results for the Darwin drift

TABLE 1. Base parameters: $L_{\parallel}/L_{\perp} = 2$, $\lambda = 2$, $L = 10$, $a = \lambda/2\pi$.

Shape	Q_{\perp}/V	v_D (from equation)	v_D (from simulations)
Base	-0.15	-6.10	-6.11
$L_{\parallel}/L_{\perp} = 0.5$	-0.68	-12.74	-12.78
$L_{\parallel}/L_{\perp} = 3.5$	-0.08	-5.24	-5.33
$L = 5$	-0.17	-6.36	-6.30
$L = 15$	-0.14	-5.98	-6.03
$\lambda = 0.5$	-0.20	-6.76	-6.78
$\lambda = 3.5$	-0.04	-4.71	-4.68
$\lambda = 8, L = 20$	0.58	3.04	3.07

Darwin drift:



$$Q_{\perp} = -\frac{1}{2} \int_S f_z \rho^2 dS$$

$$v_D = \frac{4\pi Q_{\perp}}{V} - v_*,$$

$$v_* = v_s + v_{wake}$$

Entrainment

Tracer moves in loops far from swimmer
Entrainment close to the swimmer

Volume of fluid moved by the swimmer:

Darwin drift:

$$v_D = \frac{4\pi Q_{\perp}}{V} - v_*,$$
$$v_* = v_s + v_{wake}$$

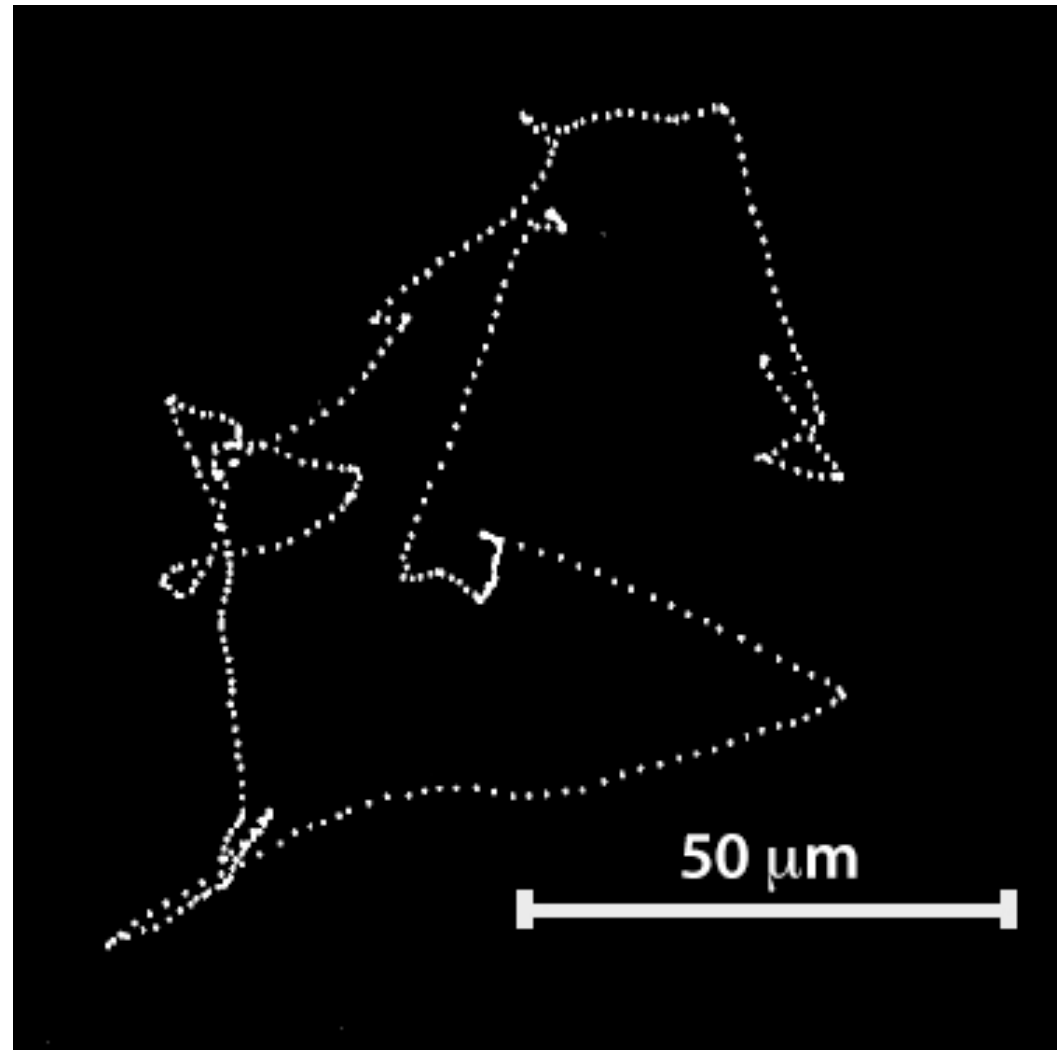
$$D_{entr} \approx \frac{1}{6} n V a \frac{4\pi}{3} a^3$$

?? enhanced diffusion and loops ??



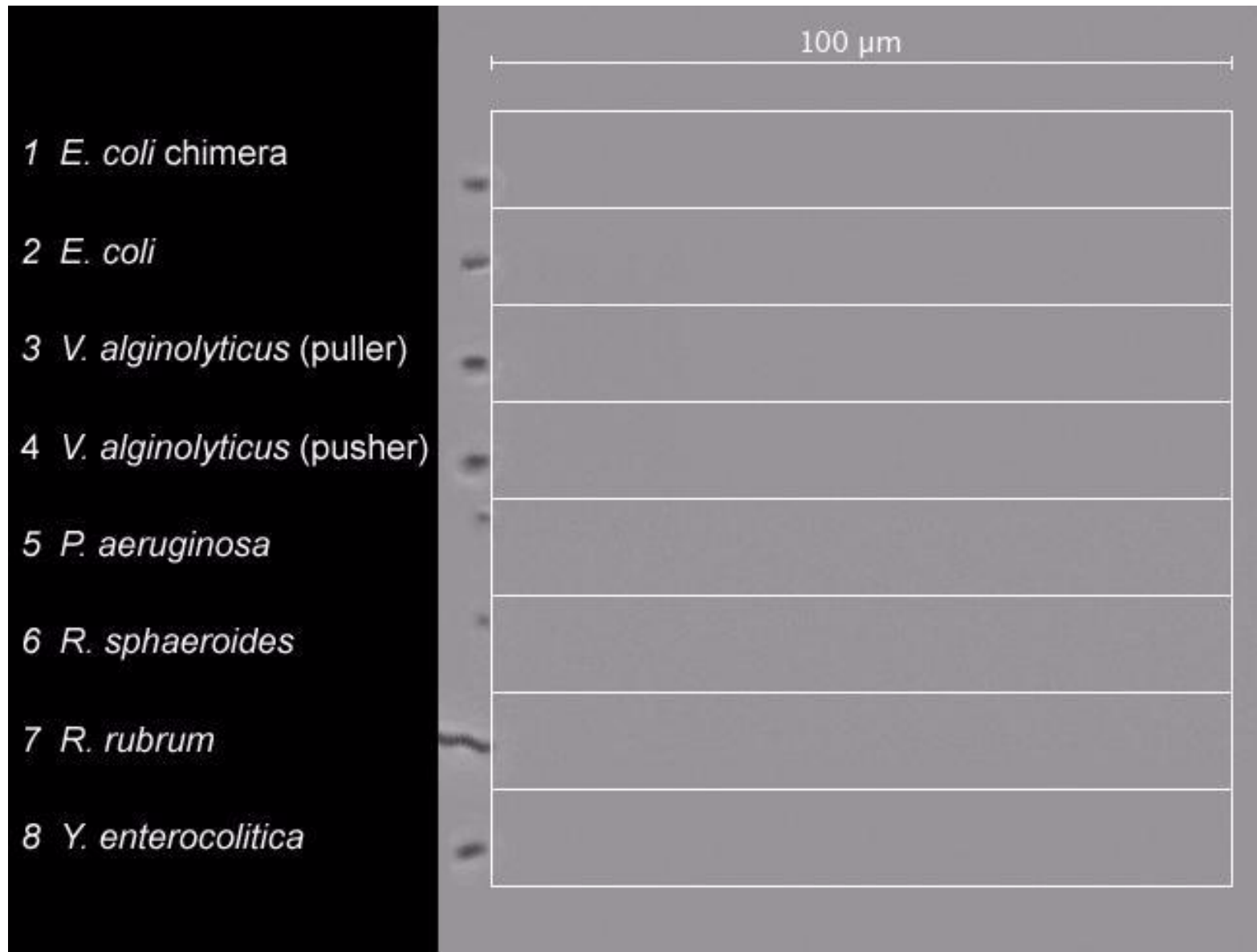
Entrainment

Swimmer re-orientations

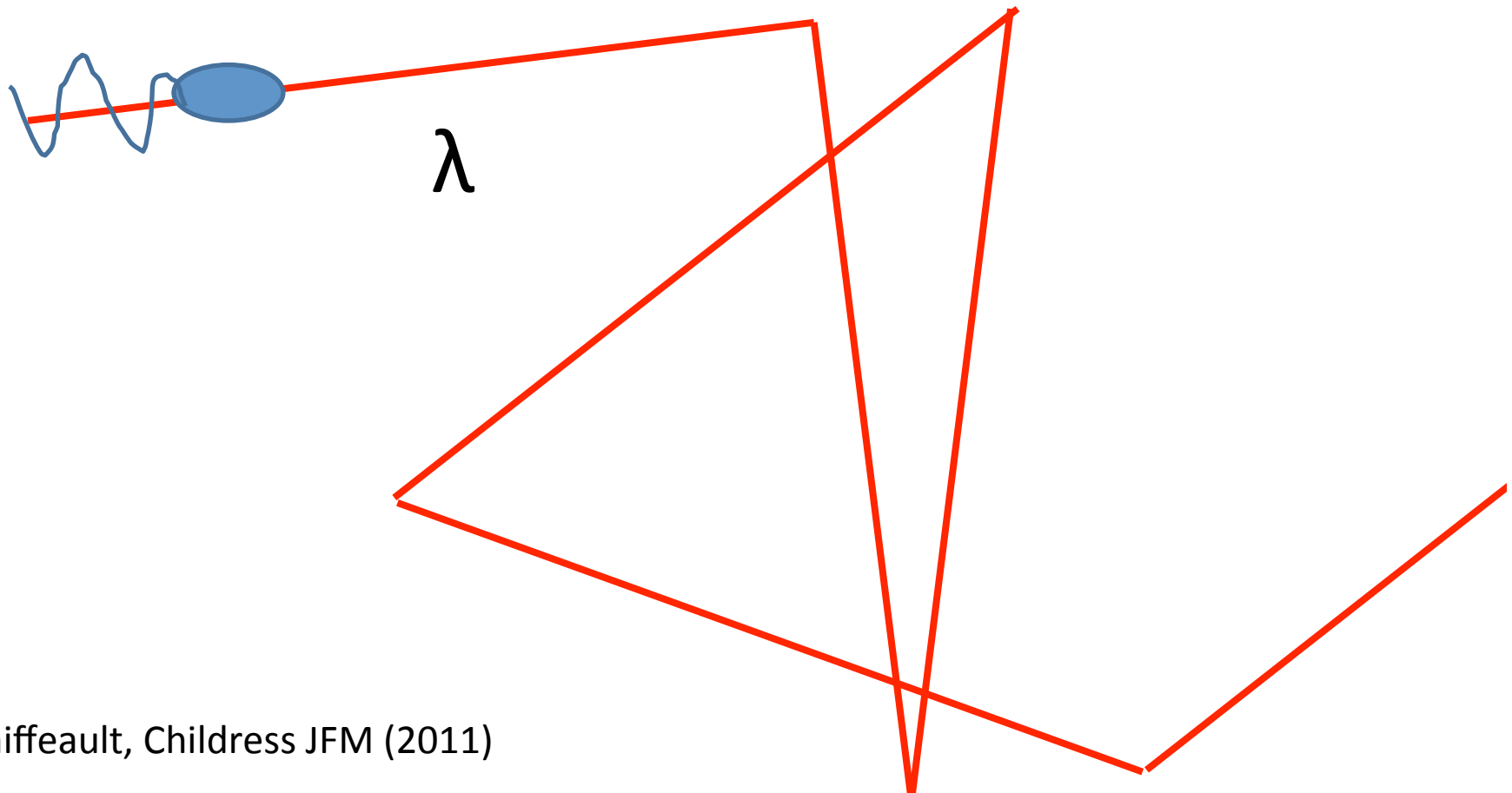
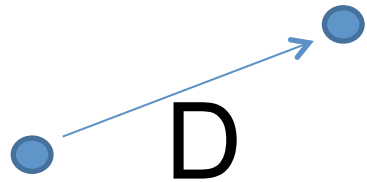


E-coli tracks: Howard Berg

!!!!!! Bacterial Olympics: 100 micrometres !!!!

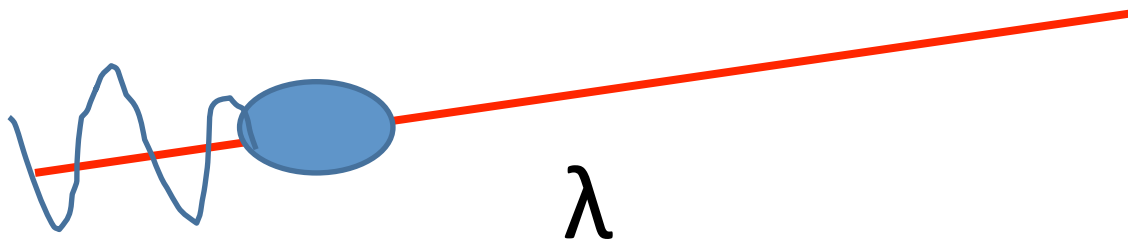
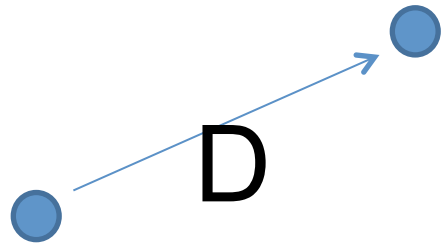


Random reorientations



Lin, Thiffeault, Childress JFM (2011)

Random reorientations



Diffusion constant for random reorientations

Dipolar swimmer 3D

$$D_{rr} = \frac{4\pi}{3} \kappa_m^2 n V a^4$$

- Independent of swimmer run length for dipolar swimmers in 3D
- Distribution of tracer run lengths converges to a Gaussian

Fluid mixing by curved trajectories of microswimmers, D.O. Pushkin and J.M. Yeomans, Phys. Rev. Lett. **111** 188101 (2013).

Entrainment

Random reorientations

Dipolar swimmer, $d=3$

$$\frac{\boxed{D_{rr}}}{D_{entr}} \approx \frac{\tilde{\kappa}^2 n V a^4}{n V a^4} \sim \tilde{\kappa}^2$$

What is missing?

Swimmer-swimmer interactions

Fluctuations

Diffusion in films

Experiments

Diffusion of particles in an active suspension has contribution from entrainment, random swimmer reorientations and thermal fluctuations.

Lecture 1: The mathematics and physics of bacterial swimming

1. Low Re and the Stokes equations

2. The Scallop theorem

one active particle

3. Dipolar flow fields

4. Multipole expansion for the Stokes equations

Lecture 2: Applications

1. Swimming in Poiseuille flow and ...taxis

2. Stirring by microswimmers

Lecture 3: Continuum models of dense active matter

lots of active particles

Lecture 4: Active turbulence and lyotropic active nematics